

Direct Drive Servomotors

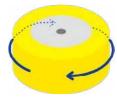
Sigma-7 200 V Series



Product Overview

SGM7D





Outer Rotor with Core

Ideal for applications that require high torque, high precision and high rigidity.

- High inertia
- Built-in high-resolution (24-bit) encoder
- A high allowable load moment of inertia ratio enables application to large loads
- Large center aperture provides more space for wiring connections

SGM7F





Inner Rotor with Core

SGM7E





Coreless, Inner Rotor

Ideal for applications that require downsizing and a shorter takt time.

- Medium inertia
- Built-in high-resolution (24-bit) encoder
- Compact size with small rotor diameter
- Greater speed and torque stability enable high-speed, high-frequency positioning

Ideal for applications that require smooth movement withput speed fluctuations.

- Low inertia
- Built-in high-resolution (24-bit) encoder
- Smooth operation without speed fluctuations achieved through coreless structure with low cogging

Range Overview

	SGM7D	SGM7F	SGM7E			
Outer diameter of motor (mm)	107 – 264	100 – 360	135 – 290			
Rated torque (Nm)	1.3 – 240	2 – 200	2 – 35			
Maximum torque (Nm)	5 - 400	6 - 600	6 – 105			
Maximum speed (min ⁻¹)	48 - 360	250 - 600	250 – 500			
Supply Voltage	200 V					
Encoder	24 bit (multiturn and incremental)					



Open for challenging Applications

YASKAWA provides equipment for a broad range of applications and offers support in all engineering tasks. This way YASKAWA will find the perfect solution for common tasks and complex automation challenges.

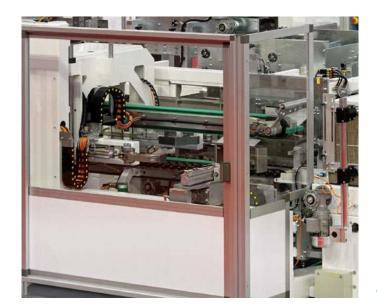
- Quick and easy set-up and no configuration effort these are the benefits of the YASKAWA out-of-the-box solutions.
- In case you want to upgrade a solution, the whole Sigma-7 system can easily be used for any new task.

Complete Solutions

YASKAWA offers comprehensive customized automation solutions with powerful hardware, including controller, visualization, drive concept and industrial robots.

Our motion control products are developed to control all functions in machine process control including motion control, PLC functionality, I/O, sequential logic and process algorithms. Controller integration lowers system cost, increases performance, reduces required panel space and unifies programming.

Process monitoring and diagnostics are inherent features of our platform. These advancements increase product throughput and reduce machine downtime. With our systems in the field, productivity increases by more than 200 % have been achieved. Smoother running and e-stop recovery routines lessen mechanical wear and reduce down time.



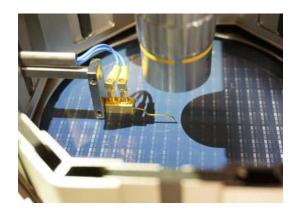
For a wide Range of Applications





- Machine tools
- Printing rolls
- Indexers
- Sorters and bonders





- Rotary tables
- Semiconductor manufacturing
- Direct torque transmission
- And many other applications

Sigma-7 Direct Drive Motors Highlights

High precision and performance



Built-in high-resolution 24 bit encoder

With 16.77 million pulses per revolution, we provide the industry-top level of positioning precision.



Improved machine performance

The motion mechanisms stiffness is greatly improved. YASKAWA direct drive motors allow high radial and axial forces. The motors are also available in a high mechanical precision version.

High efficiency and energy saving



Short acceleration and settling time

In combination with the Sigma-7 drive and the performance of the linear motor, the after motion settling time will be shortened significantly.



No gear losses

There is no reduction like a gear or a belt in efficiency due to a power transmitting mechanism, which helps save energy for the machine. A high amount of poles guarantees a smooth running characteristic of the motor. No gear losses.

High reliability and compact design



Ease of operation and high reliability

YASKAWA products stand for high reliability by best performance. YASKAWA Direct Drive Motors are easily handled by the use of the intergrated auto tuning functions.



Direct coupling design and construction

A direct drive servomotor is an actuator that directly transmits the rotational force of the motor so that couplings and other support mechanisms are not required, which saves installation space.

Combination of Direct Drive Servomotors and SERVOPACKs

Direct Drive Servom	otor Model	Rated torque	Instantaneous Max. Torque	SERVOPA		
Direct Drive Servom		[Nm]	[Nm]	SGD7S-DDDD		
	SGM7D-30F	30	50			
	SGM7D-58F	58	100			
	SGM7D-90F	90	150	120A*1		
	SGM7D-1AF	110	200			
	SGM7D-01G	1.3	4			
	SGM7D-05G	5	6	2R8A*1, 2R8F*1		
	SGM7D-08G	8	15			
	SGM7D-18G	18	30			
	SGM7D-24G	24	45	120A*1		
	SGM7D-34G	34	60	120/1		
	SGM7D-45G	45	75			
	SGM7D-03H	3	4	2R8A*1, 2R8F*1		
	SGM7D-28I	28	50	2110/11, 21101		
	SGM7D-70I	70	100			
SGM7D	SGM7D-1ZI	100	150			
(With core, outer rotor)	SGM7D-12I	130	200			
	SGM7D-2BI	220	300			
	SGM7D-2DI	240	400	120A*1		
	SGM7D-2DI SGM7D-06J	6	8	120A		
	SGM7D-08J SGM7D-09J	9	o 15			
	SGM7D-095 SGM7D-18J	18	30			
	SGM7D-185 SGM7D-20J					
	SGM7D-203 SGM7D-38J	20 38	45			
	SGM7D-385 SGM7D-02K		60			
		2.06	5			
	SGM7D-06K	6	10			
	SGM7D-08K	8	15	2R8A*1, 2R8F*1		
	SGM7D-06L	6	10			
	SGM7D-12L	12	20	1004*1		
	SGM7D-30L	30	40	120A*1		
	SGM7E-02B	2	6	2R8A, 2R1F		
	SGM7E-05B	5	15	ZROA, ZRIF		
	SGM7E-07B SGM7E-04C	7	21			
		4	12		2R8A	
SGM7E	SGM7E-10C	10	30			
(Coreless, inner rotor)	SGM7E-14C	14	42	2R8A, 2R8F		
	SGM7E-08D	8	24			
	SGM7E-17D	17	51			
	SGM7E-25D	25	75			
	SGM7E-16E	16	48	5R	5A	
	SGM7E-35E	35	105			
	SGM7F-02A	2	6	2R8A, 2R1F		
	SGM7F-05A	5	15		0004	
	SGM7F-07A	7	21		2R8A	
	SGM7F-04B	4	12	2R8A, 2R8F		
	SGM7F-10B	10	30			
	SGM7F-14B	14	42		5A	
	SGM7F-08C	8	24	2R8A, 2R8F	2R8A	
SGM7F	SGM7F-17C	17	51		5A	
(With core, inner rotor)	SGM7F-25C	25	75		6A	
	SGM7F-16D	16	48		5A	
	SGM7F-35D	35	105	7R6A*2, 120A	7R6A*2	
			135	7R	6A	
	SGM7F-45M	45				
	SGM7F-45M SGM7F-80M	80	240	120A		
	SGM7F-45M SGM7F-80M SGM7F-1AM	80 110	240 330	120A 180A		
	SGM7F-45M SGM7F-80M SGM7F-1AM SGM7F-80N	80 110 80	240 330 240	120A	_	
	SGM7F-45M SGM7F-80M SGM7F-1AM	80 110	240 330	120A 180A	_	

*1: An SGM7D Servomotor is used together with an FT-specification SERVOPACK. The following SERVOPACK models can be used.
SGD7S-DDDDDADDF82D
SGD7S-DDDD0ADDF83D
SGD7S-DDD020ADDF84D

*2: Use the derated values given in the table below for the rated output and rated motor speed of this combination.

SGM7D (Outer Rotor, with Core)

digit

Model designations

SGM	17D	-	30	F	7	С	4	1
Direct Drive Servomotors			1st + 2nd	3rd	4th	5th	— 6th	_ 7th
1st + 2n	d digit -	Rate	ed Output		3rd dig	it - Serv	omotor Ou	uter Diamet
Code S	Specifica	tion			Code	Spec	ificatior	า

3

7 F

01 1.30 Nm 02 2.06 Nm 03 3.00 Nm 05 5.00 Nm 06 6.00 Nm 08 8.00 Nm 09 9.00 Nm 12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	Code	Specification
03 3.00 Nm 05 5.00 Nm 06 6.00 Nm 08 8.00 Nm 09 9.00 Nm 12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 12 100 Nm 12 130 Nm 28 220 Nm	01	1.30 Nm
05 5.00 Nm 06 6.00 Nm 08 8.00 Nm 09 9.00 Nm 12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	02	2.06 Nm
06 6.00 Nm 08 8.00 Nm 09 9.00 Nm 12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 28 220 Nm	03	3.00 Nm
08 8.00 Nm 09 9.00 Nm 12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	05	5.00 Nm
09 9.00 Nm 12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	06	6.00 Nm
12 12.0 Nm 18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	08	8.00 Nm
18 18.0 Nm 20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	09	9.00 Nm
20 20.0 Nm 24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	12	12.0 Nm
24 24.0 Nm 28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	18	18.0 Nm
28 28.0 Nm 30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1C 130 Nm 2B 220 Nm	20	20.0 Nm
30 30.0 Nm 34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	24	24.0 Nm
34 34.0 Nm 38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	28	28.0 Nm
38 38.0 Nm 45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	30	30.0 Nm
45 45.0 Nm 58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	34	34.0 Nm
58 58.0 Nm 70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	38	38.0 Nm
70 70.0 Nm 90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	45	45.0 Nm
90 90.0 Nm 1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	58	58.0 Nm
1Z 100 Nm 1A 110 Nm 1C 130 Nm 2B 220 Nm	70	70.0 Nm
1A 110 Nm 1C 130 Nm 2B 220 Nm	90	90.0 Nm
1C 130 Nm 2B 220 Nm	1Z	100 Nm
2B 220 Nm	1A	110 Nm
	1C	130 Nm
2D 240 Nm	2B	220 Nm
	2D	240 Nm

3rd digi	t - Servomotor Outer Diameter						
Code	Specification						
F	264 mm dia.						
G	160 mm dia.						
Н	116 mm dia.						
	264 mm dia.						
J	150 mm dia.						
K	107 mm dia.						
L	224 mm x 224 mm						
Note:							
	rect Drive Servomotors are not						
	available with holding brakes This information is provided to exp-						

This information is provided to explain model numbers. It is not meant to imply that models are available for all combinations of codes.

The SGM7D-01G, -05G, and -03H are available only with high mechanical precision.

4th digit - Serial Encoder Code Specification

*	24-bit multiturn absolute encoder
*	24-bit incremental encoder

* Both multiturn absolute encoder and incremental encoder can be used as a single-turn absolute encoder by setting parameters.

5th digit - Design Revision Order Code Specification

Standard Version

oth digit - Flange										
Code	Mounting	Servomotor Outer Diameter Code (3rd digit)								
	wounting	F	G	Н	1	J	Κ	L		
4	Non-load side with cable on side	\checkmark	~	\checkmark	-	-	-	~		
5	Non-load side with cable on bottom	~	√*	-	~	\checkmark	\checkmark	-		

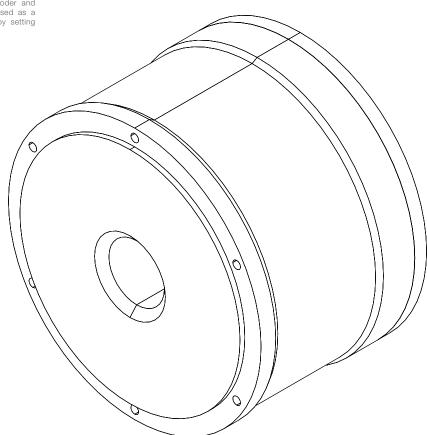
Applicable models

* SGM7D-01G and -05G are not available with a cable extending from the bottom.

7th digit - Options

Code	Specification
1	Standard mechanical precision
2	High mechanical precision*3

* The SGM7D-01G, -05G, and -03H are available only with high mechanical precision.



More detailed information, technical specifications and accessories (e.g. cables) can be found in our main Sigma-7 200 V catalog. Please contact your YASKAWA representative or find the documents on our website.

SGM7E (Inner Rotor, Coreless)

Model designations

SGN	Л7Е	-	02	В	7	А	1	1				
Direct Dri Servomot			1st + 2nd	3rd	4th	5th	— 6th	_ 7th	digit			
1st + 2	2nd digit -	Rate	ed Output	i i	3rd digit - Servomotor Outer Diameter							
Code	Specifica	tion			Code	Spec	ification	ı				
02	2 Nm				В	135 n	nm dia.					
04	4 Nm				С	175 n	175 mm dia.					
05	5 Nm				D	230 mm dia.						
07	7 Nm				Е	290 mm dia.						
08	8 Nm											
10	10 Nm				4th di	git - Se	erial End	coder				
14	14 Nm				Code	Spec	ificatior	1 I				
16	16 Nm				7*	24-bi enco		rn absol	ute			
17	17 Nm				F*		t increm	ental				
25	25 Nm				F	enco	der					
35	35 Nm							e encode be used				
								oder by s				

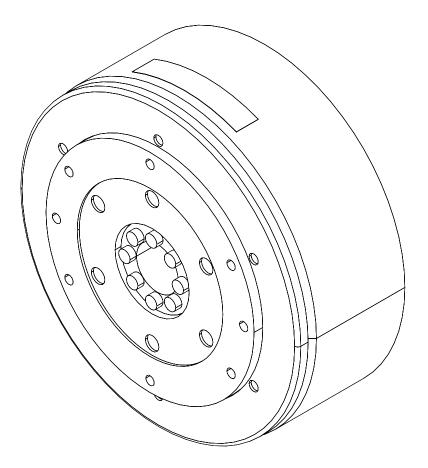
parameters.

5th dig	git - Design Revision Order
Code	Specification
А	Standard version
6th dig	git - Flange
Code	Mounting
1	Non-load side
4	Non-load side with cable on side
7th dig	git - Options
Code	Specification
1	Without options
2	High machine precision (runout at end of shaft and runout of shaft surface: 0.01 mm)

Note

1. Direct Drive Servomotors are not available with holding brakes.

2. This information is provided to explain model numbers. It is not meant to imply that models are available for all combinations of codes.



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SGM7F (Inner Rotor, with Core)

Model designations

SGN	M7F	-	02	А	7	А	1	1				
Direct Dri Servomot			1st + 2nd	3rd	4th	5th	— 6th	_ 7th	digit			
1st + 2	2nd digit -	Rate	ed Outpu	it	3rd dig	it - Serv	omotor O	uter Diam	eter			
Code	Specifica	ation			Code	Spec	ificatior	ı				
Small	Capacity				А	100 r	nm dia.					
02	2 Nm				В	135 n	nm dia.					
04	4 Nm			С	175 r	175 mm dia.						
05	5 Nm			D	230 r	230 mm dia.						
07	7 Nm				Μ	280 r	280 mm dia.					
08	8 Nm				Ν	360 r	nm dia.					
10	10 Nm											
14	14 Nm				4th di	git - Se	erial End	coder				
16	16 Nm				Code	Spec	ification	1				
17	17 Nm				7*			rn absol	ute			
25	25 Nm				1	enco	der t increm	ontol				
35	35 Nm				F*	enco		ental				
Mediu	m Capaci	ty			* Both	multiturr	absolut	e encode	r and			
45	45 Nm							be used				

incremental encoder can be used as a single-turn absolute encoder by setting parameters.

5th digit - Design Revision Order						
Code	Spe	cifi	catior	ı		
	0.1					

Standard Version А

<u> 6th digit - Flange</u> Servomotor Outer Diameter Code (3rd digit) Code Mounting В С D Ν Α Μ Non-load side 1 Load side 3 Non-load side Non-load side (with 4 cable on side)

Applicable models

7th	dig	jit -	Optio	ns	
-					

Code Specification

1 Without Options

High machine precision (runout at end of 2

shaft and runout of shaft surface: 0.01 mm)

Note

80

1A

1E

2Z

80 Nm

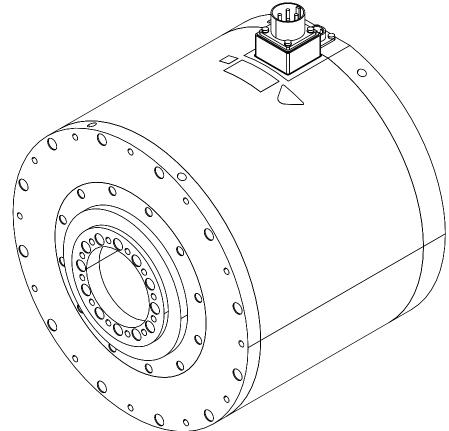
110 Nm

150 Nm

200 Nm

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